

ABSTRACT OF THE DISCLOSURE

The invention refers to a combination of a self-propelled harvester (32) and a transport vehicle (33), set up to accept crops from the harvester, which has at least one driven and at least one steered axle, wherein the transport vehicle (33) has an electronic control unit (38) which is set up to control the driven and the steered axle of the transport vehicle (33), and the control unit (38) is connected to a receiving unit which is set up to receive position data for the harvester (32) so that the control unit (38) can be operated to control the transport vehicle (33) to accept crops from the harvester (32) automatically with respect to a position of the harvester (32).

The proposal is made that the control unit (38) be operable to automatically make the transport vehicle (32) drive parallel to the harvester (32) and to be docked to it so as to be able to accept crops from the harvester (32), and that the transport vehicle (33) be unmanned.